applied optics 2

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applied optics 1: properties of light

geometrical optics polarisation and intensity of light birefringence interference diffraction of light scattering of light applied optics 2: application of light

sources and detectors of light black body radiation, Bohr's model of atom, light bulb, discharge lamp, X-ray tube, lasers, H-D curve, CCD, angiograph

polarisation of light polarisation microscope, GDx

interference and diffraction biometry of the eye, OCT

wavefronts and aberrations Seidel's aberrations, Zernike polynomials, wavefront error, classification of aberrations, WASCA

basic microscopy methods bright field, dark field, Nomarsky contrast, immersion fluid, condensor, endotellium microscope

scanning methods depth of field, confocal microscope, *HRT*, scanning techniques, *CSLO*



light sources

		atomary emission, bremsstrahlung Čerenkov radiation
type of emission	spectrum	characteristic radiation
atomary emission	line/continuous	
thermal emission	characteristic/contin.	\tilde{c} astice \tilde{c} \tilde
luminiscence	~ monochromatic	elektron
Čerenkov radiation	continuous	K charakteristické polarizace částice
annihilation	polychromatic	atom e záření záření vinoplocha
stimulated emission	(lasers)	- · · · · · · · · · · · · · · · · · · ·
black body radiation maximum of radiated $\lambda_{max} = \frac{2,898 mm}{T[K]}$ (Wie overall amount of radia $j \approx \sigma T^4$ (Stefan $\sigma = 5.67 \mathrm{x} 10^{-8}$	n energy en's law) jated energy n-Boltzmann law) Js ⁻¹ m ⁻² K ⁻⁴	Glossary.periodni.com/glossary.php?en=blackbody+radiation T = 6000 K T = 6000 K T = 5000 K T = 3000 K T = 3

light bulb



evacuated bulb with tungsten filament + nitrogen/argon atmosphere

electric current heats the filament to (2000 K - 3000 K)

cca 97% of energy is radiated in IR, only 3% in visible part of the spectrum

lifetime of bulb is limited by tungsten evaporation

for common use, light bulbs are being replaced (LED sources)



X-ray tube





using suitable mirror coating, only the central mode can be selected – laser becomes super **coherent**

by combination of meta-stable transition

spectral width and resonator modes width extremely narrow linewidth of laser is produced

concave-convex

 $R_1 \ge l$

 $R_2 = L - R_1$

apart from stimulation, laser uses a common type atomic emission

He-Ne laser

wavelength 632,8 nm, continual, laser power up to 50 mW

a mixture of helium and neon in evacuated tube

pumping is realised by starting a discharge in the tube

pumping excites mostly helium, the energy is passed to neon (meta-stable levels) by collisions



laser pumping regime application He-Ne continual, 632,8 nm basic type laser optical (discharge) (continual, 1060 nm) (N - CO₂) tattoo removal optické (ionisation) ruby laser: Al₂O₃ – Cr pulsed, 694,3 nm continual, 488 nm, 514 nm coagulation (retina) ion lasers : argon optical (discharge) continual, VIS (krypton) Nd:YAG optical pulsed, 1064 nm iridotomy ablation, LASIK excimer lasers .: ArF pulsed, 193 nm chemical reaction pulsed, 248 nm (353 nm) KrF (XeF,...) pulsed, 570-640 nm dye lasers: rhodamine 6G, tunable lasers by another laser pulsed, 390-435 nm removal of moles stilbene

gas discharge

discharge lamp: evacuated tube with electrodes, secondarily filled with gas upon **ionization**, a permanent discharge can be ignited in gas

- ionisation by voltage: glow discharge (ionisation by accelerated electrons)
- thermal ionisation: (spark) discharge

after ignition, discharges tend to be self-sustaining



low-pressure (**neon**) tube (tenths of kPa) with separate electrodes color depends on gas composition (99.5 % neon, 0.5 % argon) starting voltage about 120 V

with DC, only one electrode glows with AC, both electrodes glow (as voltage changes sign) power consumption is small

high intensity discharge

ignited by touching of the electrodes and their subsequent withdrawal

can be produced in various atmospheres

problem: high current between electrodes make them burn away (anode 4x faster than cathode)

most of the light come from heated electrodes (anode 90%, cathode 8%, discharge itself 2%)



luminiscence is a common designation for light emission following some light absorption meanwhile non-radiative de-excitation also takes place

luminescent response is delayed from absorption, for longer delays we use the term phosphorescence

co₽





within 24 hours of fluorescein application, irradiation by green lasers (Ar-ion) is avoided

fundus camera and fluorescein angiography

fluorescence: emissive response of material to illumination delayed by miliseconds red-shifted w.r.t. excitation

for longer delays (seconds or even more) we use term phosphorescence

some tissues act as natural fluorophores, short illumination then suffices to trigger the response

or, artificial fluorophore can be supplied intravenously, eg

fluorescein absorbs in blue part of the spectrum (485-500 nm) and emits in green part of the spectrum (525-530 nm)

indocyanine green (ICG) has absorbtion maximum near 800 nm and emits light near835 nm (ie. whole phenomenon takes place in IR)



illumination of retina can be achived using the fundus camera

special microscope serves as objective
strong source of flash light is needed



it is convenient to perform both measurements simultaneously





detection of light

the eye

response time 0,1s detection via electrochemical chain

photographic emulsion

- photosensitive layer of halogenides of silver (eg. AgBr)
- in reaction to illumination, the silver is reduced
- (latent image is produced amount of reduced silver too small to be visible)
- role of the **developer** (eg. Na₂S₂O₃.5H₂O) is to seek the places where silver has already been reduced and there multiply the amount of reduced silver (about billion times)
- the fixer changes the remaining AgBr into water soluble salt, which is subsequently washed away (together with gelatine matrix supporting the photosensitive layer)
- developing of the film must be stopped in due time the response both to illumination and to developing is described by the general **Hurter-Driffield** curve

photographic emulsion works also with X-ray

insensibilised films are almost insensitive to green light sensibilisation: ortochromatic, panchromatic

coloured film: three suitably sensibilised layers atop one another

detection of light

sensitivity of detectors can be measured as s[ASA]; for a correct exposition time t[s] of the observed scene the exposition need [EV] is introduced through

$$2^{EV_S} = \frac{c^2}{t}$$

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where c is the speed of the objective used. clearly, shift of exposition need by 1EV changes exposition time by factor of 2 (with c fixed)

exposition need of usual scenes is known (or can be measured), it is convenient to refer the value to a fixed detector sensitivity (say, 100ASA); for other speeds, one has

$$e^{EV_S - EV_{100}} = \frac{S}{100}$$

by combination of the two formulas one finally has

$$t = \frac{c^2}{\frac{s}{100} 2^{EV_{100}}}$$

common scenes range from $EV_{100} = 16$ (sunlit snow) to $EV_{100} = -9$ (Milky Way).

apart from exposition need, every scene also posses some exposition extent [ASA] describing the fluctuation of the forme within the scene:

dynamic range of the detectorexposition extent of the sceneexposition flexibility of the detector for the given scene









detection of light

CCD (Charge Coupled Device)

uses photoefect, descendant of a photodiode: impacting light produces free electrons, that can be counted to provide relative measure of light intensity

condition for photon capture: hf > A

the work function A is a constant of each material, usually tenths to units of eV

technically, a CCD detector is realized by a MOS type semiconductor organized into distinct electrodes



Electron packet



by suitable voltage gating the freed electrons can be held below the electrode after exposition, clocking of the voltage shifts the pixels towards read out

to achieve colored image, RGB masking is used (which decreases resolution of the chip)

photographic objective



depth of field	paprsky v okolí ohniska	objective speed c = f/d
a perfect optical system images a point object into a point image in the vicinity of this point image the rays form a cone, whose angle depends on the aperture in real optical system the image is hampered at least by diffraction	Η	01.4
the original cone with sharp tip at the image is replaced by a diffraction tunnel whose waist opens only slowly and is surrounded by diffraction minima and maxima	M	0 2
Faca/ v	M	O 2.8
$\frac{p/ane}{4\pi}$ $\frac{3\pi}{3\pi}$ length of the diffraction tunnel:	M	O 4
$\int \frac{l}{D^2} = 4c^2$		5.6
$\begin{array}{c c c c c c c c c c c c c c c c c c c $)	8
$\int \int \int \frac{d^{-1}}{2\pi} \int \frac{d^{-1}}{2\pi} \int \frac{d^{-1}}{2\pi} \int \frac{d^{-1}}{\pi} \int \frac{d^{-1}}{2\pi} \int d^{-1$	C	
plane		22

confocal microscope

patented 1957

SIMPLIFIED OPTICS OF A LSCM



principle of the method: an aperture iris is introduced into the conjugate focus to the observed point. The opening of the iris is very small, and thus strongly limiting rays from other points.

the iris is (piezo) moved, so in result, a full 3D image can be taken albeit point by point, which is slow

usually, fluorescent image is taken

the image is processed by a computer

as the image is taken point by point, confocal microscope generally belongs to the class of scanning microscopes

Heidelberg Retina Tomograph (HRT II, III), 2005



confocal microscope setup, that enhances the fundus camera possibilities is suitable for glaucoma diagnosis

provides objective information allows for progression monitoring

semiconductor laser, 670 nm field of vies 15°x15°, centred to papilla of optical nerve

scans 384x384 points 16-64 layers of depth

triple repeat (statistics)

3D image is computed automatically optic disc is segmented manually by an ophthalmologist

consequently, the computer calculates the relevant characteristics (usually in six angular segments): size and shape of disc and cup, thickness of retinal layer, excavation

data can be checked again database, important is also a comparison of left/right eye









when imaging large areas, it is convenient to take several subpictures which are aligned to final image the aberration are easier to treat for smaller fields of view, but higher mechanical stability is required

scanning optics:

mechanical (slow): Nipkow disc, piesoelectrics optical (faster, without mechanical vibrations): Kerr cell, Pokelson cell, ultrasound bending of light

for fast detection, CCD is almost exclusively used

confocal scanning laser ophthalmoscope (CSLO) 1979

objective is the eye itself

allows imaging of individual photo-receptors at retina

images about 1,5° of retina with 30 scans/second

utilisation of adaptive optics allows to eliminate the aberrations of the eye (and distinguish the types of receptors)

used for direct observing of scotoms and retinal faults

analysis of retinal neural layer thickness - GDx

the neural fibres are naturally birefringent (thanks to prolonged molecules in their shields)

for polarization microscopy, optical axes must be perpendicular to the line of sight - just the case of fibres at retina

as the light needs to be reflected (passing the neural layer forth and back), usually polarizer serves also as (parallel) analyser





1) after entering the birefringent fibre

$$E_{||} = E_p \cos \varphi = E_x \cos \varphi \cos(\omega t - kz)$$

$$E_{\perp} = E_p \sin \varphi = E_x \sin \varphi \cos(\omega t - kz)$$

after reflection from fibre back-side

$$E_{||} = E_x \cos \varphi \cos(\omega t - kz - 2kn_o d)$$

 $E_{\perp} = E_x \sin \varphi \cos(\omega t - kz - 2kn_e d)$

after analyser

$$E_{p||} = E_{||} \cos \varphi = E_x \cos^2 \varphi \cos(\omega t - kz - 2kn_o d)$$
$$E_{p\perp} = E_{\perp} \sin \varphi = E_x \sin^2 \varphi \cos(\omega t - kz - 2kn_e d)$$

y-axis mirro Detector **G** polygoi mirro Without Compensation With Adaptive Compensation

He-Ne

laser



infra-red pupil

position monitor

both waves are now polarized in the same direction ad thanks to small thickness of fibres ordinary and extra-ordinary rays remain coherent: interference takes place with phase shift $\delta = 2k(n_o - n_e)d$ interference of two waves: $I = I_1 + I_2 + 2\sqrt{I_1I_2} \cos \delta$ in our case

$$I = E_x^2 \left(\cos^4 \varphi + \sin^4 \varphi + 2 \cos^2 \varphi \sin^2 \varphi \cos \delta \right)$$

which can be written , using $\, E_x^2 = I_0 \,$, also as

$$I/I_0 = 1 - \sin^2 \frac{o}{2} \sin^2 2\varphi$$

for a particular fibre, $\delta = {
m konst}$, and thus rotation of polarizer produces minima and maxima of its visibility:

$$I_{\max}(\varphi = 0) = I_0 \quad I_{\min}(\varphi = \pi/4) = I_0 \cos^2 \frac{\sigma}{2}$$

hence, the thickness of the fibre can de deduced from

$$rac{I_{
m max}}{I_{
m min}} = \cos^2rac{\delta}{2}$$

as the only unknown in $\ \delta = 2k(n_o-n_e)d\,$ is the thickness $\$

the measurement of healthy tissue (top) and glaucoma affected one (bottom)





interference of light

for two monochromatic waves:

$$I = I_1 + I_2 + 2\gamma \sqrt{I_1 I_2 \cos \delta}$$

coefficient γ measures the coherence

Michelson interferometer

subtle shifting of one of the mirrors allows to measure sub-wavelength features by counting the passing fringes:

wave packets

$$E = \sum_{i=1}^{n} E_{0i} \cos(\omega_i t - k_i x + \delta_i)$$

the (coherence) length of the packet:

 $\Delta L_m = m \frac{\lambda}{2}$





the packets will (partly) interfere, if they (partly) overlap in space



visibility of the interference: $\mu = rac{I_{
m max} - I_{
m min}}{I_{
m max} + I_{
m min}}$

 $\gamma \in \langle 0,1\rangle \qquad I_1 \thickapprox I_2: \quad \mu \thickapprox \gamma$



interferometric measurement of thickness

consider Michelson interferometer with moving mirror, sample of thickness x and refractive index n we use the wave-packets picture:

the wave directly reflected packet (orange) and back-side reflected packet (green) will only interfere, when they succeed to meet both in space and time. the phase difference in flight, caused by the sample thickness can be compensated by moving the interferometer arm by scapping the full range of the arm movement, several peaks of interference visibility are obsi

by scanning the full range of the arm movement, several peaks of interference visibility are observed, from which the thicknesses of individual layers within sample can be deduced



 $\Delta d = 0$

 $\Delta d \approx 0$

 $\Delta d \approx 2nx$

higher order reflections are difficult to observe (their intensity is low)

optical biometry of the eye

IOL Master – performs interferometric measurement of structures within the eye using the wave-packets of suitable length

the method is non-contact: measurement can take place through glasses or, even through cataract



resolution in thickness: 0.02 mm





the output of measurement consists in dependence of interference visibility on the interferometer arms position

decomposition into possible reflecting surfaces is performed by a computer

the precision (stability) of the decomposition is highly improved (at sake of computational load) if multiple reflections can be taken into account

Optical Coherence Tomography (OCT), 1991

semiconductor laser diode, 800 - 1000 nm, hundreds of mW

the depth and lateral resolutions are detached:

depth resolution:
dependson packet length only
$$\ln(2)\frac{2}{\pi}\frac{\lambda_0^2}{\Delta\lambda} = \frac{2\ln 2}{\pi}\delta$$

lateral resolution: depends on optics used







RESOLUTION (log)

OCT = source of diffuse spectrum + interferometer + scanning optics

IMAGE PENETRATION (log)



two successive maxima:

$$2k(l_f - l_m) = c2\pi$$

$$2k'(l_f - l_m) = (c+1)2\pi$$

$$\Delta k = k' - k = \frac{\pi}{l_f - l_m}$$



$$\vec{x}_0 = (x_0, y_0) \quad \vec{x} = (x, y)$$

without loss of generality, we can set $y_0 = 0$
 $x_0; y_0 \qquad x; y$

based on the symmetry, rotating the system around the optical axis must produce no visible effect only combinations of scalar products $\vec{x}_0 \cdot \vec{x}_0, \vec{x} \cdot \vec{x}_0, \vec{x} \cdot \vec{x}$ can be present

wavefront aberration: $H(x_0, y_0, x, y) \to H(x_0^2, x_0 x, x^2 + y^2)$ (y₀ = 0)

in polar coordinates $x = \rho \cos \vartheta$ $y = \rho \sin \vartheta$ ρ is the aperture radius

$$H(x_{0}^{2}, x_{0}\rho\cos\vartheta, \rho^{2}) = \sum_{k,l,m} W_{klm} x_{0}^{k}\rho^{l}\cos^{m}\vartheta =$$

$$= W_{000} + W_{200}x_{0}^{2} + W_{111}x_{0}\rho\cos\vartheta + W_{002}\rho^{2} +$$

$$+ W_{400}x_{0}^{4} + W_{040}\rho^{4} + W_{131}x_{0}\rho^{3}\cos\vartheta + W_{222}x_{0}^{2}\rho^{2}\cos^{2}\vartheta +$$

$$+ W_{220}x_{0}^{2}\rho^{2} + W_{311}x_{0}^{3}\rho\cos\vartheta + \dots$$

special case: axial (point) source: $x_0=0$

$$H = \frac{1}{8}S_{I}\rho^{4} + \frac{1}{2}S_{II}x_{0}\rho^{3}\cos\vartheta + \frac{1}{2}S_{III}x_{0}^{2}\rho^{2}\cos^{2}\vartheta + \frac{1}{4}(S_{III} + S_{IV})x_{0}^{2}\rho^{2} + \frac{1}{2}S_{V}x_{0}^{3}\rho\cos\vartheta$$

the lowest (third) order terms:

spherical aberration S_I , coma S_{II} , astigmatism S_{III} , curvature S_{IV} , distortion S_V piston, tilt and defocus are not aberrations (they do not disturb point imaging) within higher orders, new types of aberrations are introduced (elliptic coma, ...) advantage of Seidel coefficients:

the overall aberration of every kind is just a sum of contributions from individual surfaces: eg. $S_I = S_I^1 + S_I^2 + S_I^3 + S_I^4 + \cdots$ etc.



transversal aberration describes change of image position within image plane

motivation: information is needed in more detail than keratograph can provide

also, axial symmetry is nor present within eye on the other hand, pupil is almost perfectly circular

Zernike polynomials (1934)

well suited for aberrations of the eye description, other systems (turbulent media, brilliant cutting) may be better described by other systems

we stat again from wavefront description using the polar coordinates $x = \rho \cos \theta$, $y = \rho \sin \theta$ in the plane of exit pupil:

$$H(\rho,\theta) = \sum_{n=1}^{k} \sum_{m=-n}^{n} W_n^m Z_n^m \qquad Z_n^m = R_n^m(\rho) \Phi_n^m(\theta)$$

drawback: information on position of the source is suppressed for a complete aberrational description, several measurements are needed

advantage: individual terms do not interfere - addition of one polynomial does not disturb the other aberrations

one Zernike polynomial comprises several Seidel aberrations, and vice versa



Hartmann-Shack sensor



278-17105791

resolution limit of the objective

resolution of common detectors: the eye (1 arc minute), photographic film (100 lines/mm), CCD (size of the pixel: 1-5 μm)



similar considerations hold for imaging of moving objects: motional blur appears (blood flow etc.)

illumination of microscopy samples

light bulbs: wolfram filament (halogen bulbs: wolfram filaments + iodine cycle)

discharge lamps: significant emission in UV intense sources + good for luminescence trigering

filters: coloured - monochromatic, can improve image sharpness gray (ND) - overall intensity tuning, can improve contrast

condenser serves to

homogenise light (intensity), creation of plane wavefront increase the numerical aperture (and thus also the resolution of microscope) allow for advanced microscopy techniques





$$d_{\min} = \frac{\lambda_0}{A_0 + A_C} = C \frac{\lambda_0}{A_0} \qquad C \approx 0.5 \div 1$$

condensers can be constructed for both transmitted and reflected light the advanced techniques are usually realised through filter wheels condenser can be the most expensive part

of the microscope





immersion objectives

through numerical aperture, the diffraction spot size depends on refractive index o the medium between objective and sample:

$$d_{\min} = \frac{1,22\lambda}{NA} = \frac{1,22\lambda}{n\sin\alpha}$$

one way of shifting the resolution limit is to use shorter wavelength light

the other is to introduce (immersion) medium with n>1 between objective and sample:

medium	n
air	1,0003
water	1,33
immersion oil	1,515
bromnaphtalene	1,658
metyleniodid	1,740

Oil Immersion and Numerical Aperture



Figure 1

the resolution enhancement upon using immersion fluids comes from collecting higher angle rays

immersion objectives are explicitly prepared for contact with fluids (and are usually marked around by a colored line)

yet another possibility is to make use of condenser

(altogether, by application of all possible improvements, about a quarter of a wavelength can be resolved)

bright filed: almost all light rays from source are used for creating an image; when no sample is present. homogeneously lit field (bright field) is observed

after sample loading, the viewed contrast is created by absorbing parts of the sample

samples with neglibigle absorption contrast get invisible using tis method

dark field: a hollow light beam is created within condenser, which reaches sample at an oblique angle, which is designed such, that these rays cannot be collected by the objective

hence, only light scattered by the sample can aid in constructing the image (scattering is omni-directional)

the hollow light beam is initiated using concave mirror similar construction can be reached in reflected light



reminder: HRT also works in dark field



phase contrast (Zernike 1930, Nobel prize 1953)

samples, that exhibit both little absorption and little scattering will still be almost invisible final solution: slight changes in refractive index need to be visualised



DIC (differential interference contrast)

phase contrast

improvement of phase contrast modality: removal of the halo

especially useful for samples creating about $\lambda\!/4$ phase shift



Nomarsky contrast

